3/26/19 Lecture 1: Root systems. 31 Routs We must start on the level of Lie algebras, rother than Lie graps. Definitions  $g = [g, g] := \{ [X, Y] \mid X, Y \in g \}$ · A complex, finite dimensional Lie algebra g is semisimple if Example  $SL_{n}(\mathbb{C}) = \{X \in M_{n\times n}(\mathbb{C}) | Tr(X=0)\}$  is semisimple. ([K,Y]=XY-YX.) Det A Cartan subalgebra of a semisimple Lie algebra of is a subalg the such that · It is nilpotent, which means [In, [In, In]...] (n brackets) is zero for some n.  $h = N_{g}(h) \quad (:= \{X \in \mathcal{G} \mid [X, \mathcal{H}] \in \mathcal{H}\}) \quad (i.e., \mathcal{H} \text{ is self-normalizing})$ It's usually hard to use this definition, so here are some facts. I'll give some examples of everything in a moment. Facts . (artan subalgebras are a belian (i.e., [h, h]=0) . All Cartans are conjugate by an automorphism of g, hence they all have the same dimension, Def rk(g) := Jim(my Cartm), the cank of g. Notwin Write ad(X)(Y) = [X, Y],Then ad (X): g -> g is a linear map and so is adig -> End(g). In Fact, ad([X,Y]) = ad(X) ad(Y) - ad (Y) ad(X), so ad is a representation of ~Ende(Y). Fact ad(h) is simultaneously diagonalizable, meaning there's a basis {X;};=1 of g such that:  $\forall$  Hen,  $\forall$  i,  $\exists \lambda_{H_i} \in \mathbb{C}$  st.  $aJ(H)(X_i) = [H, X] = \lambda_{H_i} X_i$ Note that the map  $\alpha_i: H \mapsto \lambda_{H,i}$  is a line map  $\mathcal{H} \to \mathbb{C}$ , i.e., a character of  $\mathcal{H}$  (because  $[aH_i + bH_i, \lambda_i] = a[H_i, \lambda_i] + b[H_i, \lambda_i]$ = $(\lambda_{H_{U'}} + (\lambda_{H_{U'}})))$ Definition The nonzero xi's are called the roots of g. Example (Slz.) (when  $h = \begin{pmatrix} x \\ x \end{pmatrix}$  (This is the Lie algebra of the standard maximal torus in  $SL_3(\mathbb{C})$ .) Note dim h = 2. The basis of X's is. The six elementary matrices  $E_{ij}$  for  $i \neq j$ .  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ ,  $E_{iz} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 &$ We check?  $a_{1} \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left[ \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right] \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) \left( E_{12} \right) = \left( \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} \right) \left( E_{12} \right) \left( E_{12}$ So if we define  $\alpha_{12}$  = the root for  $(E_{12})$ , then  $\alpha_{12}(\alpha_1, \alpha_2) = \alpha_1 - \alpha_2$ . Similarly,  $d_{ij} \begin{pmatrix} a_{i} \\ a_{ij} \end{pmatrix} = a_{i} - a_{j}$ , for if , are the other roots. Example (ah). h=(\*...\*). The simultaneous eigenbasis consists of Eis, isi=1,...,n, iti, wong with any basis for h. The roots are  $a_{ij} = simultaneous$  eigenvalue of h on  $E_{ij}$ , given by  $a_{ij} \begin{pmatrix} a_1 & \\ & a_n \end{pmatrix} = a_i - a_j$ . Fact A subabular to of a semisimple. Lie abeliar of is a Cartin (=) it is maximal abelian and ad (th) is simultaneously diagonalizable. ("Maximal abelian" means it is contained in no larger abelian subalgebra, not that it has maximal dimension among abelian subalgebras.)

\$2. Properties of roots Fix a Cartan th in a semisimple Lie algebra g. Let I be the (Finite) set of roots of h. Note  $\overline{I} \subseteq h^{\vee} := Hom_{\mathcal{C}}(\mathcal{K}, \mathcal{C})$ . (1) For a e D. let ga = {Xey | [M, X] = ~ (M) X & MEh} be the a-eigenspace. Then Jim ga = 1. (In the she example, gain= (E: E: ) (2) (Root space decomposition) J = h ⊕ ⊕ Ja. (3) If a is a root, then so is -d. (In the shreekample, -dij=dij) (4) I spons tr. (In the she example, {x:, i+1 | i=1,..., n-1} is a spanning set.) Something more general than (3) is true. To explain it, we need to talk about the Killing form, which one needs anyway to justify the facts which have been said already. Def The Killing form is the symmetric bilinear form on g  $(\chi, \gamma) = T_r(\alpha J(\lambda) \cdot \alpha J(\gamma))$ Note all(x) ad (Y) is a linear endomorphism of the vector space g, so we can just take the trace as usual. The Killing form is symmetric because Tr(AB)=Tr(BA) Thm (Cartan) of is semisimple ( , . ) is nondegenerate. East If g is semisimple, then (.,) restricts to a perfect pairing on any Cartan h. Therefore we get a canonical isomorphism him by HHH (H, ), and hence also a perfect pairing (.,.): hi x him (, given explicitly by  $\langle \langle H_{1,1} \rangle \langle H_{1,1} \rangle \rangle = \langle H_{1,1} H_{1} \rangle$ (5) IF X, B are routs, so is the reflection of B across the hyperplane perpendicular to d, i.e.,  $\alpha, \beta \in \Phi$  =>  $S_{\alpha}(\beta) := \beta - \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \ll e \Phi$ Example Let's compute Sx12 (\$23) for Alz.  $\mathcal{U}_{3}.$   $\int_{\alpha_{12}} (\alpha_{13}) = \alpha_{13} - 2 \frac{\langle \alpha_{12}, \alpha_{23} \rangle}{\langle \alpha_{12}, \alpha_{12} \rangle_{6}} \alpha_{12}.$ To compute the Killing Form, we need to make explicit the identification him by H++(H,.), and so we need to computer (...) on a basis of &. Let  $H_{12} = \begin{pmatrix} 1 & -1 \\ 0 \end{pmatrix}$ ,  $H_{23} = \begin{pmatrix} 0 & 1 \\ -1 \end{pmatrix}$ . A basis of  $\mathfrak{L}_3$  consists of  $H_{12}$ ,  $H_{23}$ ,  $\mathsf{E}_i$ ; for  $i \neq j$ . One computes ensity:  $_{\mathcal{O}_{n}} \int_{\mathcal{O}_{n}} \left( H_{12} \right) \left( E_{1j} \right) = \begin{cases} 2 E_{12} & i_{1j} = 1/2 \\ 1 E_{13} & i_{1j} = 1/3 \\ -1 E_{13} & i_{2j} = 2/3 \\ -2 E_{21} & i_{1j} = 2/1 \\ -2 E_{21} & i_{2j} = 2/1 \\ -2 E_{21} & i_{2j} = 2/1 \\ -2 E_{21} & i_{2j} = 2/2 \\ -2 E_{22} & i_{2j} = 2/2 \\ -2 E_{22} & i_{2j} = 3/2 \\ -2 E_{22} & i_{2j}$  $ad(H_{12})(4) = ad(H_{23})(h) = 0$ . Therefore,  $(H_{12}, H_{23}) = T_{\Gamma} (ad(H_{12}) ad(H_{23})) = (2)(-1) + (1)(1) + (-2)(2) + (-2)(1) + (-1)(-1) + (1)(2) = -2 + 1 - 2 = -6.$ Just nultiply the numbers we got above. Similarly,

$$\langle H_{12}, H_{12} \rangle = 4 + 1 + 1 + 4 + 1 + 1 = 12 = \langle H_{23}, H_{23} \rangle.$$

$$\begin{split} \text{Let} \quad \Psi_{12} &= \left( \Psi_{12}, \cdot \right) \in \frac{10}{4L}, \quad \Psi_{23} = \left( \Psi_{23}, \cdot \right) \in \frac{10}{4L}, \quad \text{Then} \\ \Psi_{12} \begin{pmatrix} \alpha_{1} & \alpha_{2} & \alpha_{3} \end{pmatrix} = \left( \Psi_{12} \begin{pmatrix} \alpha_{1} & \alpha_{1} & \alpha_{2} \\ & & & & & & & \\ \end{array} \right) \\ &= \left( \Psi_{12} \begin{pmatrix} \alpha_{1} & \alpha_{2} & \alpha_{3} \end{pmatrix} + \left( \Psi_{12} \begin{pmatrix} 0 & \alpha_{1} + \alpha_{2} & -\alpha_{1} - \alpha_{1} \end{pmatrix} \right) \\ &= \alpha_{1} \begin{pmatrix} \Psi_{12} \begin{pmatrix} \Psi_{12} \end{pmatrix} + \left( \alpha_{1} + \alpha_{2} \end{pmatrix} \begin{pmatrix} \Psi_{12} \end{pmatrix} \begin{pmatrix} \Psi_{12} \end{pmatrix} \\ &= \alpha_{1} \begin{pmatrix} \Psi_{12} \end{pmatrix} + \left( M_{12} \end{pmatrix} + \left( M_{12} \end{pmatrix} \begin{pmatrix} \Psi_{12} \end{pmatrix} \end{pmatrix} \\ &= \left( 2 \alpha_{1} - 6 \left( \alpha_{1} + \alpha_{2} \right) \right) \\ &= \left( 2 \alpha_{12} \begin{pmatrix} \alpha_{1} - \alpha_{1} \end{pmatrix} \right) \\ &= \left( 2 \alpha_{12} \begin{pmatrix} \alpha_{1} - \alpha_{1} \end{pmatrix} \right) \\ &= \left( 2 \alpha_{12} \begin{pmatrix} \alpha_{1} - \alpha_{1} \end{pmatrix} \right) \end{split}$$

So,  $\Psi_{12} = 6 d_{12}$ . Similarly,  $\Psi_{23} = 6 d_{23}$ . Therefore,

$$\left\langle \alpha_{12}, \alpha_{13} \right\rangle = \left\langle \frac{1}{6} \varphi_{12}, \frac{1}{6} \varphi_{23} \right\rangle = \frac{1}{36} \left( \Psi_{12}, \Psi_{23} \right) = \frac{1}{36} \left( -6 \right) = \frac{-1}{6} \\ \left\langle \alpha_{12}, \alpha_{12} \right\rangle = \left\langle \frac{1}{6} \varphi_{12}, \frac{1}{6} \varphi_{12} \right\rangle = \frac{1}{36} \left\langle \varphi_{12}, \varphi_{13} \right\rangle = \frac{1}{36} \left( 12 \right) = \frac{1}{3} ,$$

and so

$$\frac{2(\alpha_{12}, \alpha_{13})}{(\alpha_{12}, \alpha_{12})} = \frac{2 \cdot (-1/6)}{1/3} = -1$$

Thus we have computed the number we were looking for, and we can substitute back into the definition of  $S_{\alpha_{12}}(\alpha_{23}) = d_{23} - \frac{2(\alpha_{12}, \alpha_{23})}{(\alpha_{12}, \alpha_{12})} \alpha_{12} = \alpha_{23} + \alpha_{12}$ But this should be a root, i.e.,  $S_{\alpha_{12}}(\alpha_{23})$  should equal  $\alpha_{13}$  for some i.i. However, we see that  $(\alpha_{12} + \alpha_{12}) \begin{pmatrix} \alpha_{1} & \alpha_{1} \\ \alpha_{1} & \alpha_{2} \end{pmatrix} = \alpha_{12} - \alpha_{3} + \alpha_{1} - \alpha_{2} = \alpha_{1} - \alpha_{3} = \alpha_{13} \begin{pmatrix} \alpha_{1} & \alpha_{1} \\ \alpha_{1} & \alpha_{2} \end{pmatrix}$ . So  $(S_{\alpha_{12}}(\alpha_{13}) = \alpha_{13}, \beta_{13})$ 

We can compute Skiz on any other root as well.

$$S_{\alpha_{12}}(\alpha_{1j}) = \begin{cases} -\alpha_{12} & i, j = 1/2 \\ \alpha_{13} & i, j = 1/3 \\ \alpha_{13} & i, j = 2/3 \\ \alpha_{13} & i, j = 2/3 \\ \alpha_{12} & i, j = 2/3 \\ -\alpha_{13} & i, j = 3/1 \\ -\alpha_{13} & i, j = 3/2 \\ -\alpha_{13} & i, j = 3/2 \\ \end{cases} = ij \quad b/c \quad i \neq s \quad n \quad reflection$$

In general,  $S_{\alpha} \in O(\mathcal{H}, (\cdot, \cdot))$  (the orthogonal group),  $S_{\alpha}(\Psi) := \Psi - \frac{2(\alpha, \Psi)}{2(\alpha, \alpha)} \alpha$ , for general  $\Psi \in \mathcal{H}$ . Def  $W_{\overline{\Phi}} := subgroup of O(\mathcal{H}, (\cdot, \cdot))$  generated by  $S_{\alpha}$ 's for  $\alpha \in \overline{\Phi}$ .  $W_{\overline{\Phi}}$  is called the <u>Weyl group</u> of  $\overline{\Phi}$ . (6)  $W_{\overline{\Phi}}$  is a finite group.

Note 
$$\frac{2(d,\alpha)}{(d,\alpha)} = 2$$
, so  $S_{\alpha}(\alpha) = \alpha - 2d = -\alpha$ . Therefore  $(5) \Rightarrow (3)$ 

(7)  $\forall \alpha, \beta \in \Phi, \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \mathbb{Z}, \text{ ad in fact,}$  $7\frac{2(\alpha,\beta)}{(\alpha,\infty)} \in \{0,\pm1,\pm2,\pm3\}$ . In particular, (8)  $\alpha \in \mathbb{I} \Rightarrow n\alpha \notin \mathbb{I}$  for any  $n \neq \pm 1$  (because if |n| > 1, then  $\frac{2(\alpha, n|\alpha)}{(\alpha, \alpha)} = 2|n| \ge 4$ .) (9) The Z-span of I is a lattice in the R-span of  $\overline{Q}$ . (... ) is real-valued and positive definite on the R-span of  $\overline{I}$ . Det A cost system is an R-vector space V together with a pos. Let. symmetric pairing (', ') and a solset I IV st. (1) 0∉∮ (In practice, this will be the real form of our the given by the R-spin of  $\overline{D}$ ) (b)  $\not\in$  spans V(c)  $\forall \alpha, \beta \in \overline{I}$ ,  $\overline{\langle \alpha, \alpha \rangle} \in \mathbb{Z}$ I is <u>reduced</u> if also (e)  $\alpha \in \mathbb{I} \Rightarrow 2 \propto \notin \mathbb{I}$ Remark with some effort, finiteness of Wor (defined the same may) and the fact that  $\frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \{0, \pm 1, \pm 2, \pm 3, \pm 4\}$ , can be shown for general root systems. Furthermore, 2(x, 67 = ±4 = ±2d, so if I is reduced, then (8) follows for I. (9) follows from the theory of simple roots (see the next section.) Summery Given a semisimple Lie algebra C, a Cartan h Eg is a subalgebra which is maximal abelian and such that ad(h) is simultaneously Jagonalizable. We get a reduced root system  $(V, \overline{\Phi}, \langle \cdot, \cdot \rangle)$  by:  $. I = \{ nonzero sinultaneous eigenvalues of ad(31) on <math>y \} \subseteq W$ . V= R-spon of € (so V@RE=h) · (·, ·) is induced from the Killing form: (K,Y) = Tr (ad(K)·ad(Y)) for X, Y < 22 (the operator ad (K)·ad(Y) acting on g) and then  $\langle \langle K, \cdot \rangle, \langle Y, \cdot \rangle \rangle := \langle K, Y \rangle$  puts  $\langle \cdot, \cdot \rangle$  on  $V \in \mathcal{H}$ . Then  $\forall \alpha \in \Phi$ ,  $\forall \alpha = \alpha$ -eigenspace (or root space) is 1-dimensional. } 3. Positive and simple roots. Fix a root system  $(V, \overline{I}, (\cdot, \cdot))$ . Fix any total order ">" on V such that!  $\cdot (\Psi_1, \Psi_2) = (\Psi_1 + (\Psi_2))$ · Exactly one of the following holds for any QEV. 4 >0, -4 >0, 4=0. Say Q is positive if Q>0. For instance, fixing a basis  $\varphi_1, \dots, \varphi_r$  of V, we can take  $\sum_{i=1}^r a_i \varphi_i > \sum_{i=1}^r b_i \varphi_i$  if  $a_i = b_{1/2} a_i > b_{1/2}$  some i. Let  $\overline{\Phi}^+ = \{\alpha \in \overline{\Phi} \mid \alpha > 0\}$  - the positive roots. Then  $\overline{\Phi}^- := \{-\alpha \mid \alpha \in \overline{\Phi}^+\}$  has  $\overline{\Phi}^- \cup \overline{\Phi}^+ = \overline{\Phi}$  and  $\overline{\Phi}^- \cap \overline{\Phi}^+ = \phi$ . Def A root is simple if it is positive, and cannot be written as a sum of two positive roots. simple roots. Let  $\Delta C \mathcal{I}^{+}$  be the set of

Fads • # Δ = dim V.
• Any β∈ D<sup>+</sup> can be (uniquely) written β = ∑n α, nα ≥ 0 ∀α∈Δ. Hence any r∈ D can be written as g= Emaa, where the mais all have the same sign.
• Since D, hence D<sup>+</sup>, spans V, it follows that Δ is R-linearly independent, and that the nais above are unique.
• The choice of ordering we started with has an effect on Δ. But:

The Wy acts simply transitively on the set of all possible  $\Delta s$ . If > and > give the same  $\Delta$ , then they give the same  $J^+$ . The lexicographical ordering described above with  $\Delta$  as a basis (my order on  $\Delta$ ) makes  $\Delta$  simple. Example ( $\Delta l_n$ ). -  $d_{12}$ ,  $d_{23}$ , ...,  $\alpha_{n-1}$ , are simple for the lexicographical ordering they induce.

- Note there are n-1=rk(sh) of them.

Lecture 2. Rat system (cartined).  
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Event A finite diversional) sensingle Lie algebra of and a (artin 1659 gives rise to a set of roots  

$$\overline{\mathfrak{g}} = \{\operatorname{renzero} \operatorname{simultaneous} \operatorname{communus} \operatorname{communus}$$

Def I is <u>reducible</u> if there are solspaces V<sub>1</sub>, V<sub>2</sub> SV with subsets I; SV; such that V=ViOV2, I=I, III2, and (ViiI; (:, )) are rout systems. Otherwise, I is <u>irreducible</u> <u>Ruk</u> Simple Lie algebras ~ reduced irreducible root systems ~ (onnected Dynkin diagrams. <u>Then</u> Two reduced, irreducible root systems having the same Dynkin diagram are isomorphic (meaning there's a linear isomorphism between vector spaces preserving the form and sending roots fijectively to roots.)

. The possible connected Dynkin diagrams are the usual ones.

. The Dynkin diagram of g determines g up to isomorphism.

35. Recovering & From its Dynkin Diagram We want to find the root system given just the single roots. We'll use the following tool. Def Let a BED. The rest string of a containing B is Stry (B)= {P+ na | neZ and B+nae ] Eacts . Stra(B) has no gaps. · Let p, q ∈ Z st. β+nx ∈ Stra(β) €) p≤n≤q. Then • If  $\alpha, \beta \in \Delta$ , then  $\alpha - \beta \notin \overline{d}$ , and so p = 0 and  $q = -\frac{2 (\alpha, \beta)}{(\alpha, \alpha)}$ • If  $\mathcal{T} = \sum_{r \in \Lambda} n_{x} \alpha \in \mathcal{I}^{+}$ , with  $\Sigma \cap \alpha > 1$ , then we can find  $\beta \in \Delta$  such that  $\mathcal{T} - \beta \in \mathcal{I}$ . These facts will let us recover &. How about the Lie bracket? Eacts, If a, B, a+B & J, then [Jx, Jr] = Ja+B.  $\left[g_{\alpha},g_{-\alpha}\right]=\mathbb{C}\cdot\mathsf{H}_{\alpha}\subseteq\mathsf{h}^{\mathsf{V}}, \text{ where } \left(\mathsf{H}_{\alpha},\cdot\right)=\mathsf{d}\left(\cdot\right), \text{ (In fact } \left[\mathsf{E}_{\alpha},\mathsf{E}_{-\alpha}\right]=\left(\mathsf{E}_{\alpha},\mathsf{E}_{-\alpha}\right)\mathsf{H}_{\alpha}\right)$ Now for a ED, let.  $h_{\alpha} = \frac{2}{(\alpha, \alpha)} H_{\alpha},$ · exega be any nonzero vector,  $f_{\alpha} \in g_{-\alpha}$  st  $(e_{\alpha}, f_{\alpha}) = \frac{2}{(\alpha, \alpha)}$ With these choices,  $C \cdot h_a + Ce_a + Cf_a \cong Al_2; \quad h_a \mapsto ('-i), e_a \mapsto (\circ \circ), f_a \mapsto (\circ \circ), \text{ and}$  $\cdot \left[h_{\alpha}, e_{\alpha}\right] = \frac{2}{\langle \alpha, \alpha \rangle} \alpha(H_{\alpha}) e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle H_{\alpha}, H_{\alpha} \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle (H_{\alpha}, \cdot), (H_{\alpha}, \cdot) \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = 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= \frac{2}{\langle \alpha, \alpha \rangle} \langle \alpha, \alpha \rangle e_{\alpha} = \frac{2}{\langle \alpha, \alpha \rangle$  $\cdot \left[ h_{x} f_{x} \right] = -2f_{x}$ •  $\left[e_{\alpha}, f_{\chi}\right] = \left(e_{\alpha}, f_{\chi}\right) H_{\alpha} = \frac{2}{(R_{\alpha})} H_{\alpha} = h_{\alpha}$ The (Secre) The vectors {ha, ca, fal a E } generate g as a Lic algebra with precisely the following relations."  $(1)[h_{x}, h_{p}] = 0$ (2)  $[l_{\alpha}, f_{\beta}] = \delta_{\alpha\beta} h_{\alpha}$  $(3) \left[ h_{\alpha}, e_{\beta} \right] = \frac{\ell(\alpha, \beta)}{(\alpha, \alpha)} c_{\beta}$ (4)  $[h_{\alpha}, f_{\beta}] = -\frac{2(\alpha, \beta)}{(\alpha, \alpha)} f_{\beta}$  (1 plus lungth of  $Str_{\alpha}(\beta)$ )  $(5) (A J(e_{\alpha}))^{(-(1(\alpha,\beta)/(\alpha,\alpha)))} e_{\beta} = 0$   $(6) (A J(e_{\alpha}))^{(-(1(\alpha,\beta)/(\alpha,\alpha)))} f_{\beta} = 0$ We give an instructive example on the next page.

Example (32) Let 32 have Drakin diagram ( a longer). Find It. We have, by the diagram. 2 (d. B) 2(4,1) 2

$$\frac{(\alpha, \alpha)}{(\alpha, \alpha)} = -1, \quad \frac{(\beta, \beta)}{(\beta, \beta)} = -5,$$

$$p_{=0, \beta=1}$$

$$p_{=1} \qquad p_{=0, \beta=3}$$

$$p_{=1} \qquad p_{=1} \qquad p_$$

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β} Note that since  $\alpha + \beta \in Str_{\alpha}(\beta)$ , we have  $Str_{\alpha}(\alpha + \beta) = Str_{\alpha}(\beta)$ . Similarly,  $Str_{\beta}(\alpha) = Str_{\beta}(\alpha + \beta) = Str_{\alpha}(\alpha + \beta) = Str_{\alpha}(\alpha + \beta)$ Then we try taking Straorp (new roots) to generate more roots, repeat until we can't find new ones, then all roots are exhausted. We compute. Stra(a+2p): d+d+2p=2(a+p) ∉J by reducedness; -d+d+2p=2B∉J. No new roots.  $\operatorname{Str}_{\alpha}(\alpha+3\beta): -d+d+3\beta=3\beta\notin \overline{1} \Rightarrow p=0, \quad S_0 \quad p+q=q=-\frac{2(\alpha,d+3\beta)}{(\alpha,\alpha)}=-\left(\frac{2(\alpha,\beta)}{(\alpha,\alpha)}+3\frac{2(\alpha,\beta)}{(\alpha,\alpha)}\right)=-\left(2-3\right)=1, \quad S_0 \quad \alpha+\alpha+3\beta=2\alpha+3\beta\in \overline{1}.$ This gives us one more root to try." Stc p(2x+3p); -β+2x+3p=2(x+B)¢ €, β+2x+3p=2(x+2p) € €. No new roots. We find  $\mathbf{\tilde{D}}^{+} = \{ \alpha_{1}\beta_{1}, \alpha_{1}\beta_{2}, \alpha_{1}\beta_{2}, \alpha_{1}\beta_{3}, \alpha_{2}\beta_{3}, \alpha_{2}\beta_{3},$ 

So  $\lim_{t\to\infty} g_2 = \# \Delta + 2 : \# \underline{0}^+ = (4, \text{ and } a \text{ basis is})$ ha, ha, ex, ep, [ex, eb], [ep, [ex, ep]], [ep, [ep, [ep, [ex, ep]]] [ex, [ep, [ex, ep]]]), sure brackets with for, fp. Serre relations + Jacobi identity give all possible brackets. For example.  $[f_{\alpha}, [e_{\alpha}, e_{\beta}]] = - [e_{\beta}, [f_{\alpha}, e_{\alpha}]] - [e_{\alpha}, [e_{\beta}, f_{\alpha}]]$  $= - \left[ \mathcal{C}_{\beta} - h_{\alpha} \right] - 0$  $= - \frac{2(\alpha,\beta)}{(\alpha,\alpha)} C\beta$ = Cp.

Lecture 3. Reductive Groups. 4/9/19 Fix a field kSC. Def A linear algebraic group over a field k is reductive if its unipotent radical (ic., the largest closed, connected, normal, unipotent subgroup is trivial. Here, linear means there's an embedding G->GLn for some n, and vaipatent news there's an embedding G->(".\*). If G is reductive, then conter semisingle  $\cdot \left[ ic \ 6 = iq = 3q \ \Theta \left[ q \right], q \right]$ • G is semisimple => G is reductive. ("G is semisimple" mems "g is semisimple.") 31 Root John To classify reductive groups, we need slightly more info than for semisimple. Lie algos. We'll need four pieces of data. Def A torus is an algebraic group T over k Tr = 6m some r 20. T is <u>split</u> if T=Gm (over k instead of K.) Think: U(1) over R is a circle, not on  $\mathbb{R}^{\times}$ , But  $U(2)^{\mathbb{C}} \cong GL_1(\mathbb{C}) = Gm(\mathbb{C})$ . So U(1) is a nonsplit torus over R. Fix G a connected reductive group over ki and fix a maximal turus T = G Assumption & is selit, meaning T is split for some choice of T, which we fix. Here are the four ingredients. - (Laracturs: Let X=X\*(T):= Ham (T, Gm). (homemorphisms of alg groups) Remark hi= LieT is a Carton in g= LieG, and Jen[g, y] is a carton in [g,g]. Then if X: T-Gm is a character, JX: h-k=lie Em is a churacter of h. -Roots: GGY, and T is simultaneously diagonalizable on Lie G. Let I = {roots} = {simult eigenvalues for TGLie G. ] = X. Note: Roots are trivial on ZG). Remark If  $x \in \mathbb{I}$ , then  $dx:h \to k$  is a root of g, i.e., dx | hn (g, g) is a root of [g, g], and dx is trivial on  $B_g$ . - (achwacters : X=X \*(T):= Hum(Gm, T) - Cororts: YaEI, chouse root vectors Ex, E. E [9,9] Eg for da, -da. ] unipotent subgroups Ux, U-d with Lie Utd=k. Etd The subgroup Ha generated by Ux, U-x, T has derived group [Mx, Mx]=: Gx = SL2 or PSL2. Then 3! d' (Fm - Gx st dod = (K+1 x2). This is the coroot associated with d. let I':={\au'| \cells. This is the set of coroots. Now define a pricing  $X \times X' \rightarrow Z$  by  $(X, \Psi) = n$ , where  $\Psi \circ X : G_m \rightarrow G_m$  is  $\chi \mapsto \chi'$ . (so  $(\alpha, \alpha'') = 2$ .) This is a perfect pairing. (X, €, X<sup>v</sup>, €<sup>v</sup>) is an example of:

by A need below is a quadraptic 
$$(X, \overline{p}, X', \overline{p}'')$$
 with  $X, X''$  for ablic gamps a perfect value  $(-1, 2, 2, 4, 4) = 2$ , and a bisedian  $\overline{2} - \overline{2}''$  deaded by  $x_1 - x_2''$  such that:  
•  $V \neq \overline{e}, \overline{b}, (-4, 4') = 2$   
•  $V \neq \overline{e}, \overline{b}, (-4, 4') = 2$   
•  $V \neq \overline{e}, \overline{b}, (-4, 4'') = 2$   
•  $V \neq \overline{e}, \overline{b}, (-4, 4'') = 2$   
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•  $V \neq \overline{b}, \overline{b}, (-4, 4'') = 2$   
•  $V \Rightarrow \overline{b}, V = V = 1$   
•  $V \Rightarrow \overline{b}, V = V = 1$   
•  $V \Rightarrow \overline{b}, V = \overline{b}, \overline{b$ 

Note ZE= 2X = X, lot ZEV= X"

$$\underbrace{E_{0}}_{l_{1}} \left( \begin{array}{c} P \in L_{1} \right), \quad T = \left\{ \begin{pmatrix} \alpha & \\ b \end{pmatrix} \right\}_{=}^{2} \left\{ \begin{pmatrix} c & \\ 1 \end{pmatrix} \right\}_{=}^{$$

and

$$\underbrace{\mathbb{P}} = \{2^{\infty} i j \\ X' is sporeded by e^{v}, where e^{v}(c) = {c \atop 1}, \\ We have  $\mathbb{A}_{n}^{v}(u) = {a \atop 1}, e^{u} = (a^{v} + 1), \\ because then  $\mathbb{A}_{n}^{v}(u) = a^{v}$ , so  
 $\underline{\mathbb{P}}^{v} = \{2e^{v}\}$   
Note and  $\mathbb{Z} = X, but \mathbb{Z} = \mathbb{Z}^{v} \neq X^{v}.$   
Note and  $\mathbb{Z} = X, but \mathbb{Z} = \mathbb{Z}^{v} \neq X^{v}.$   
Note and  $\mathbb{Z} = X \otimes \mathbb{Z}$ .  $\mathbb{Z}^{v} = 2X^{v} \neq X^{v}.$   
Note and  $\mathbb{Z} = X \otimes \mathbb{Z}$ .  $\mathbb{Z}^{v} = 2X^{v} \neq X^{v}.$   
Note and  $\mathbb{Z} = X \otimes \mathbb{Z}$ .  $\mathbb{Z}^{v} = 2X^{v} \neq X^{v}.$   
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Note and  $\mathbb{Z} = X \otimes \mathbb{Z}^{v}.$   $\mathbb{Z}^{v} = X \otimes \mathbb{Z}^{v}.$   
Note and  $\mathbb{Z} = X \otimes \mathbb{Z}^{v}.$   $\mathbb{Z}^{v} = X \otimes \mathbb{Z}^{v}.$   
It  $V = \mathbb{Q} = X \otimes \mathbb{R}$ . Define  $(V, \mathbb{Y})^{v} = (X, \mathbb{Y})^{v}.$  Then  $(u, \mathbb{P})^{v} = \frac{2e^{u} \otimes \mathbb{P}^{v}}{(\mathbb{Z} \mathbb{P}^{v})}.$  Notice  $(V, \mathbb{E}, \{x, v\})$  is a cool system, and  
is the real system of  $\mathbb{Q}, \mathbb{Q}$ .  
The system of  $\mathbb{Q}, \mathbb{Q}$ .  
The system of  $\mathbb{Q}, \mathbb{Q}^{v}.$   
Note that solves real enductions over  $k$  we classified up to im by their nort dota.  
 $\mathbb{Z}$  harded is:  
 $\mathbb{Z}$  harded is:  
 $\mathbb{Z} = \frac{1}{2e^{u} \log 1} = \frac{1}{$$$$

 $\mathbf{\bar{p}} \in \left\{ \mathbf{\dot{-}} \mathbf{a}_{12} \right\}$ 

$$\rho = \begin{pmatrix} \mathbb{B} & \mathcal{K} \\ \mathbb{B} \end{pmatrix}, \quad M_{\rho \in \mathcal{I}} \begin{pmatrix} \mathbb{B} & 0 \\ \mathbb{B} \end{pmatrix}, \quad N_{\rho} = \begin{pmatrix} \mathbb{I} & \mathcal{K} \\ \mathbb{B} \end{pmatrix},$$

There we three other standard parabolics, obtained from  $\theta = \{\alpha_{23}, \alpha_{34}\}, \{\alpha_{12}\}, and \{\alpha_{34}\}.$ 

$$\begin{array}{l} \lader M. Escolar Sens. \\ (1) The default senses. \\ (2) The default senses. \\ (3) The default senses. \\ (3) The default senses. \\ (4) E. Senses. \\ (5) The default sen$$

The (Langlands, Shahidi) Assume P, P' are maximul. Let  $W(P, P') = \{w \in W(G, T) \mid w(\theta) = \Theta'\}$ . Then

$$E_{p'}(g,f,s) = \begin{cases} f_{s}(g) & W(P,P') = \{1\} \quad (s_{0} \quad \theta = \theta') \\ \int_{N'(A)} f_{s}(Wn'g) \, dn' & W(P,P') = \{W\}, \quad bot \quad \theta \neq \theta' \\ f_{s}(g) + \int_{N'(A)} f_{s}(Wn'g) \, dn' & W(P,P') = \{1,w\} \end{cases}$$
Hue,  $WP'w'' = P^{-1}$ 
otherwise

Iden of proof

$$E_{p'}(9,f,s) = \int_{N'(\omega) \setminus N'(N)} \sum_{\substack{\forall \in \text{Rendew}}} f_{s}(\forall n'9) dn'$$

$$= \cdots = \int_{N'(\omega) \cap \forall n'} \sum_{\substack{\forall \in \text{Plance}(N) \setminus N'(n)}} f_{s}(\forall n'9) dn'$$

Use

$$\mathcal{G}(\mathbb{Q}) = \bigcup_{w \in \mathcal{W}(\mathcal{G},T)} \mathcal{P}(\mathbb{Q}) \cup \mathcal{P}(\mathbb{Q})$$

to split this into a sum over w. Most terms unish by cuspidwity of or; what's left is what's above. El 33 Intertwining operators.

$$\begin{array}{l} \underbrace{\operatorname{Rm}}_{\operatorname{M}} & \operatorname{If} \quad \pi_{\operatorname{P}} \otimes_{\mathcal{I}}^{\prime} \pi_{\operatorname{V}}, \quad \operatorname{Hen} \quad (f_{\operatorname{P}}(\pi)) = \otimes_{\mathcal{I}}^{\prime} (f_{\operatorname{P}}(\pi)). \\ \underbrace{\operatorname{Def}}_{\operatorname{For}} \quad \operatorname{We} \operatorname{W}(G_{1}T), \quad f \in (f_{\operatorname{P}}(\pi)), \quad \operatorname{Jefine} \quad \operatorname{He} \quad \operatorname{intertwining} \quad \operatorname{operators} \quad by \\ & \operatorname{M}_{\operatorname{V}} (\pi_{\operatorname{V}} \otimes)(f_{\operatorname{V}}) = \int_{\operatorname{We} \cap \operatorname{W} \cap \operatorname{W}^{-1}}(g_{1}) \quad f(\operatorname{W}^{-1} \cap g) \, dn \quad (f = \bigotimes_{\operatorname{P}} f_{\operatorname{V}}) \\ & \operatorname{M} (\pi_{\operatorname{V}} \otimes)(f) = \int_{\operatorname{We} \cap \operatorname{W} \cap \operatorname{W}^{-1}}(g_{1}) \, f(\operatorname{W}^{-1} \cap g) \, dn \end{array}$$

Thin

$$\begin{split} \mathsf{M}_{\mathsf{v}}(\mathsf{N}_{\mathsf{v}},\mathsf{w}) &: \mathsf{L}_{\mathsf{p}}^{\mathsf{G}}(\mathsf{N}_{\mathsf{v}}) \longrightarrow \mathsf{L}_{\mathsf{p}}^{\mathsf{G}}(\mathsf{w}_{\mathsf{N}}), \qquad \mathsf{M}(\mathsf{N}_{\mathsf{v}},\mathsf{w}) &: \mathsf{L}_{\mathsf{p}}^{\mathsf{G}}(\mathsf{n}) \longrightarrow \mathsf{L}_{\mathsf{p}}^{\mathsf{G}}(\mathsf{w}_{\mathsf{N}}), \qquad \mathsf{G}^{\mathsf{-}}\operatorname{cquivariantly}, \text{ where} \\ & \mathsf{w}_{\mathsf{N}}(\mathsf{m}_{\mathsf{v}}) = \mathsf{N}_{\mathsf{v}}(\mathsf{w}^{\mathsf{v}}\mathsf{m}_{\mathsf{v}}\mathsf{w}) \quad \mathrm{ad} \quad \mathsf{w}_{\mathsf{N}}(\mathsf{m}) := \mathsf{N}(\mathsf{w}^{\mathsf{-}}\mathsf{m}_{\mathsf{v}}), \end{split}$$

 $\frac{F_{nct}}{Note} If \left( \begin{matrix} G \\ p \end{matrix}\right) is onramified and <math display="block"> f_{v} \in C_{p}^{G}(\sigma_{v})^{K_{v}}, \text{ then } M_{v}(\sigma_{v}, w) f_{v} \in C_{p}^{G}(w_{N,v})^{K_{v}} \\ \underline{Note}, If w p'w' = p^{-}, \text{ then } w^{-1}N^{-}w = N_{B} \cap w^{-1}N^{-}w, \text{ so}$ 

$$\int_{N'(A)} f_{s}(wng) dn' = \int_{(N_{B}nw^{-}W^{-}w)(A)} f_{s}(wng) dn = M(\pi, w^{-1}) f_{s}$$

So to compute Ep, it suffices to compute  $M(tr, w^{-1})f_s$ . We can do this easily at unramified places. <u>Recall</u> (Satake) If  $\pi_v$ -unr, then we get  $\chi_{\pi_v}:T(Q_v)/T(Z_v) \rightarrow \mathbb{C}^k$  via the Satake transform. <u>Then</u> (Gindikin-Karpelevich, Langlands) Let  $\{\omega\} \subseteq S = set$  of places away from which  $\pi$  and  $C_p^{\varepsilon}(\pi, s)$  are unr. Let  $f_s = \bigotimes_{v \in S} f_{v,s} \bigotimes_{v \in S} f_{v,s}^v$ . Let  $\Sigma$  be the roots in N. View  $\chi_v \equiv \chi_{\pi_v}$  in  $\chi(T) \otimes \mathbb{C}$ . Then  $M(\sigma_{T, w'}) f_s = (\prod_{v \in S} \prod_{v \in S} \frac{(1-(\chi_v, \alpha'')p_v^{-1} = S(\Omega p, \alpha''))^{-1}}{(1-(\chi_v, \alpha'')p_v^{-1} = S(\Omega p, \alpha''))^{-1}}) (\bigotimes_{v \in S} M_v(\pi_v, v^{-1})f_{v,s}) \otimes \bigotimes_{v \in S} f_{v,v',s}^v$ . <u>Observation</u> (Tits) Let  $H_s = \sum_{n \in S} h_{nv} \in L^{\frac{1}{2}}(T^{\vee}(\mathbb{C}))$ ,  $\Pi \subseteq Lie(G^{\vee}(\mathbb{C}))$  spinned by  $\{\alpha' \mid \alpha \text{ in out in } M\}$ . Let  $\alpha_{i, i}$  is  $i_{i}, ..., n_i$  be the eigenvalues of  $a_0(H_b)$ on  $H_i$   $H_i$  eigenspaces,  $\Gamma_i$  the reps of  $G^{\vee}$  on  $\Pi$ . Then the product abuve is  $\frac{L^{\frac{1}{2}}(u, s, \pi_i, \tau_i')}{(S(1+\alpha_i, s, \pi_i, \tau_i'))}$ 

$$\begin{split} \underbrace{\underbrace{\underbrace{\underbrace{\underbrace{S}}}_{i} \underbrace{\underbrace{\operatorname{Examples}}_{i}}_{i} & \underbrace{\underbrace{S}}_{i} \underbrace{\operatorname{Examples}}_{i} & \underbrace{\underbrace{\operatorname{Ex}}_{i} \underbrace{S}}_{i} \underbrace{\operatorname{Then}} & M = GL_{2} \times GL_{2}, \quad Let \quad \pi, \pi' \text{ be cusyibil automorphic forms on } GL_{2}, \\ \underbrace{\underbrace{\underbrace{C}}_{i} = P_{i} \quad \operatorname{Then}}_{i} & W(P_{i}) = (1, w) \text{ where } w = \underline{a}_{i} \le a_{i} \le a_{i} \le a_{i} \le a_{i} \ldots Here, \\ & w(x_{i}) = d_{i}, \quad w(x_{i}) = d_{i}, \quad w(x_{i}) = -d_{i} - d_{i} -$$

- terms of intertwining operators.
- Eisenstein series can be defined for my  $v \in X(T) \otimes \mathbb{C}$ . We'd get E(g, f, v). We just studied the case v = s pp.
- · E(9, f, v) has mero, continuation and satisfies a functional equation.

$$F(g,f,s) = F(g, M(n,w)f, -s)$$
 (maxil particle case)

00

$$E(9, f, v) = E(9, M(n, w)f, vv)$$
 (general case)

This implies the meromophic continuation and a functional equation for the constant derm.

. One can try to leverage this to study analytic properties of the L-functions in the constant term. This is the Langlands-Shahidi method.

It's still in

• Thires a formula for Mu at v=00. You get a product of quotients of P-factors, in terms of a; r; and the Longlands parameters of 2700. This is related to Marish-Chandra's C-function.